

7.5: Periodic and Piecewise Continuous Input Functions

Theorem 1. (Translation of the t -axis)

If $\mathcal{L}\{f(t)\}$ exists for $s > c$, then

$$\mathcal{L}\{u(t-a)f(t-a)\} = e^{-as}F(s)$$

and

$$\mathcal{L}^{-1}\{e^{-as}F(s)\} = u(t-a)f(t-a)$$

$$\text{for } s > c+a \text{ where } u(t-a) = u_a(t) = \begin{cases} 0 & \text{if } t < a \\ 1 & \text{if } t \geq a \end{cases}$$

Example 1. Find $\mathcal{L}^{-1}\{\frac{e^{-as}}{s^3}\}$.

$$\mathcal{L}^{-1}\left\{\frac{1}{s^3}\right\} = \frac{t^2}{2}. \text{ Therefore } \mathcal{L}^{-1}\left\{\frac{e^{-as}}{s^3}\right\} = u(t-a) \frac{(t-a)^2}{2} \\ = \begin{cases} 0, & t < a \\ \frac{1}{2}(t-a)^2, & t \geq a \end{cases}$$

Example 2. Find $\mathcal{L}\{g(t)\}$ if

$$g(t) = \begin{cases} 0 & \text{if } t < 3 \\ t^2 & \text{if } t \geq 3. \end{cases}$$

$$\text{Let } f(t) = t^2$$

$$\text{Then } g(t) = u(t-3)f(t-3) \quad \text{Therefore } \mathcal{L}\{g(t)\} = e^{-3s} F(s)$$

$$\text{Let } f(t) = (t+3)^2$$

$$\text{Then } g(t) = u(t-3)f(t-3).$$

$$= e^{-3s} \left(\frac{2}{s^3} + \frac{6}{s^2} + \frac{9}{s} \right).$$

Example 3. Find $\mathcal{L}\{f(t)\}$ if

$$f(t) = \begin{cases} \cos 2t & \text{if } 0 \leq t < 2\pi \\ 0 & \text{if } t \geq 2\pi. \end{cases}$$

$$f(t) = [1 - u(t-2\pi)] \cdot \cos 2t$$

$$= \cos 2t - u(t-2\pi) \cos 2(t-2\pi).$$

$$\text{So } F(s) = \frac{s}{s^2+4} - e^{-2\pi s} \cdot \frac{s}{(s^2+4)} = \frac{s(1-e^{-2\pi s})}{s^2+4}.$$

Example 4. Consider the RLC circuit $R = 110\Omega$, $L = 1H$, $C = 0.001F$ and a battery supplying $E_0 = 90V$. Initially there is no current in the circuit and no charge on the capacitor. At time $t = 0$ the switch is closed and left closed for 1 second. At time $t = 1$ it is opened and left open thereafter. Find the resulting current in the circuit if the equation is given by

$$\frac{di}{dt} + 110i + 1000q = e(t).$$

Recall $i = \frac{dq}{dt}$; i.e. $q = \int_0^t i(\tau) d\tau$. Also $e(t) = 90[1 - u(t-1)]$.

Using the fact that $\mathcal{L}\left\{\int_0^t i(\tau) d\tau\right\} = \frac{I(s)}{s}$, we get (after transform)

$$sI(s) + 110I(s) + 1000 \frac{I(s)}{s} = \frac{90}{s}(1 - e^{-s})$$

$$\text{Then } I(s) = \frac{90(1 - e^{-s})}{s^2 + 110s + 1000} = \frac{1}{s+10} - \frac{1}{s+100} - e^{-s}\left(\frac{1}{s+10} - \frac{1}{s+100}\right).$$

$$\text{Thus } i(t) = \mathcal{L}^{-1}\{I(s)\} = e^{-10t} - e^{-100t} - u(t-1)[e^{-10(t-1)} - e^{-100(t-1)}]$$

$$= \begin{cases} e^{-10t} - e^{-100t}, & \text{for } t < 1 \\ e^{-10t} - e^{-10(t-1)} - e^{-100t} + e^{-100(t-1)}, & t \geq 1 \end{cases}$$

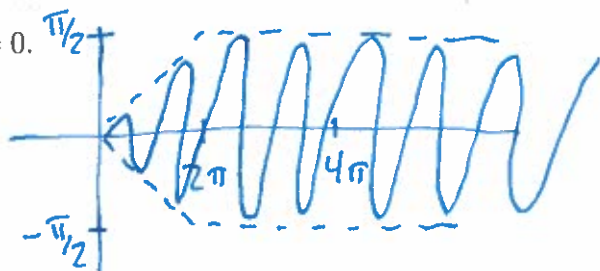
Exercise 1. A mass that weighs 32 lb is attached to the free end of a long, light spring that is stretched 1ft by a force of 4 lb. The mass is initially at rest in its equilibrium position. Beginning at time $t = 0$ (seconds), an external force $f(t) = \cos 2t$ is applied to the mass, but at time $t = 2\pi$ this force is turned off (abruptly discontinued) and the mass is allowed to continue its motion unimpeded. Find the resulting position function $x(t)$ of the mass if the resulting differential equation is

$$x'' + 4x = f(t); \quad x(0) = x'(0) = 0.$$

$$f(t) = [1 - u(t-2\pi)] \cdot \cos 2t.$$

$$\text{Thus } (s^2 + 4)X(s) = \frac{s(1 - e^{-2\pi s})}{s^2 + 4}$$

$$\text{and } X(s) = \frac{s(1 - e^{-2\pi s})}{(s^2 + 4)^2}.$$



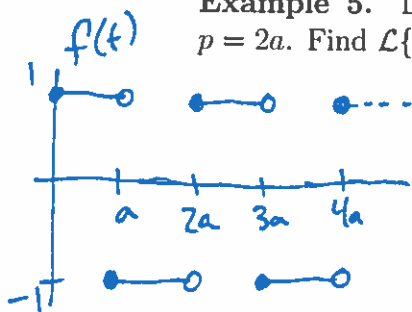
$$\text{Therefore } x(t) = \frac{1}{4}[t - u(t-2\pi)(t-2\pi)]\sin 2t = \begin{cases} \frac{1}{4}t\sin 2t, & t < 2\pi \\ \frac{1}{2}\pi\sin 2t, & t \geq 2\pi \end{cases}$$

Theorem 2. (Transforms of Periodic Functions)

Let $f(t)$ be periodic with period p and piecewise continuous for $t \geq 0$. Then the transform $F(s) = \mathcal{L}\{f(t)\}$ exists for $s > 0$ and is given by

$$F(s) = \frac{1}{1 - e^{-ps}} \int_0^p e^{-st} f(t) dt.$$

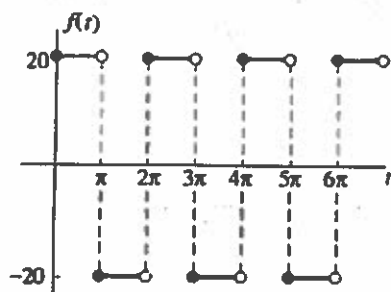
Example 5. Let $f(t) = (-1)^{[t/a]}$ be the square-wave function of period $p = 2a$. Find $\mathcal{L}\{f(t)\}$.



$$\begin{aligned} F(s) &= \frac{1}{1 - e^{-2as}} \int_0^{2a} e^{-st} f(t) dt \\ &= \frac{1}{1 - e^{-2as}} \left(\int_0^a e^{-st} dt + \int_a^{2a} e^{-st} (-1) dt \right) \\ &= \frac{(1 - e^{-as})^2}{s(1 - e^{-2as})} = \frac{1 - e^{-as}}{s(1 + e^{-as})} = \frac{1}{s} \tanh \frac{as}{2}. \end{aligned}$$

Example 6. Consider a mass-spring-dashpot system with $m = 1$, $c = 4$, and $k = 20$ in appropriate units. Suppose that the system is initially at rest at equilibrium and that the mass is acted on beginning at time $t = 0$ by the external force $f(t)$ which is the square wave function with amplitude 20 and period 2π . Find the position function $x(t)$ is the associated differential equation is

$$x'' + 4x' + 20x = f(t); \quad x(0) = x'(0) = 0.$$



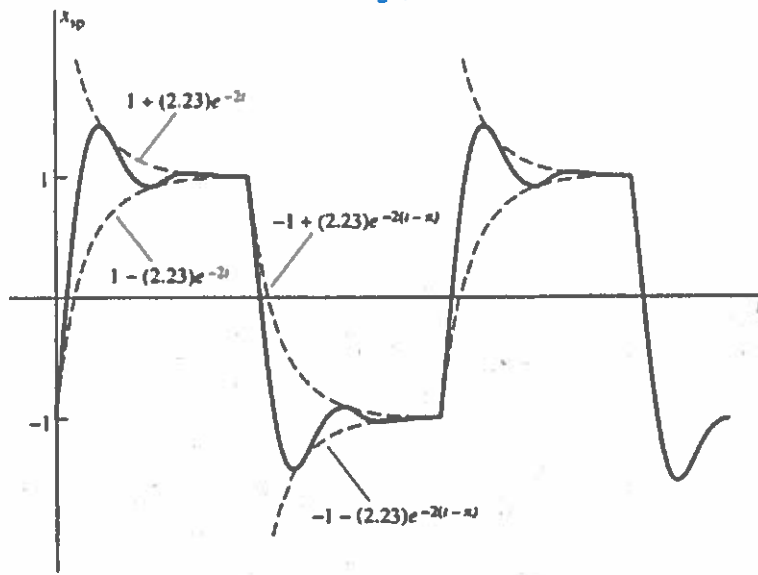
$$s^2 X(s) + 4sX(s) + 20X(s) = F(s) = \frac{20}{s} \cdot \frac{1 - e^{-i\pi s}}{1 + e^{-i\pi s}} = \frac{20}{s} + \frac{40}{s} \sum_{n=1}^{\infty} (-1)^n e^{-n\pi s}$$

$$\text{So } X(s) = \frac{F(s)}{s^2 + 4s + 20} = \frac{20}{s[(s+2)^2 + 16]} + 2 \sum_{n=1}^{\infty} (-1)^n \frac{20e^{-n\pi s}}{s[(s+2)^2 + 16]}.$$

$$\text{Noticing that } \mathcal{L}^{-1} \left\{ \frac{20}{s[(s+2)^2 + 16]} \right\} = 5e^{-2t} \sin 4t$$

(Continued on Back)

Particular Solution.



We get $\mathcal{L}^{-1}\left\{\frac{20}{s[(s+2)^2+16]}\right\} = \int_0^t \int_0^\tau e^{-2\tau} \sin 4\tau d\tau = 1 - e^{-2t} \left(\cos 4t + \frac{1}{2} \sin 4t\right)$

Therefore

$$x(t) = \left(1 - e^{-2t} \left(\cos 4t + \frac{1}{2} \sin 4t\right)\right) + 2 \sum_{n=1}^{\infty} u(t-n\pi) (-1)^n \left(1 - e^{-2(t-n\pi)} \left(\cos 4(t-n\pi) + \frac{1}{2} \sin 4(t-n\pi)\right)\right)$$

$$= \left(1 - e^{-2t} \left(\cos 4t + \frac{1}{2} \sin 4t\right)\right) + 2 \sum_{n=1}^{\infty} u(t-n\pi) (-1)^n \left(1 - e^{n\pi} e^{-2t} \left(\cos 4t + \frac{1}{2} \sin 4t\right)\right)$$

So that for $n\pi < t < (n+1)\pi$,

$$x(t) = \frac{e^{2\pi} - 1}{e^{2\pi} + 1} e^{-2t} \left(\cos 4t + \frac{1}{2} \sin 4t\right) + (-1)^n - \frac{2 \cdot (-1)^n e^{2\pi}}{e^{2\pi} + 1} e^{-2(t-n\pi)} \left(\cos 4t + \frac{1}{2} \sin 4t\right)$$

$$\approx \underbrace{(1.1139) e^{-2t} \cos(4t - 0.46)}_{\text{characteristic}} + \underbrace{(-1)^n [1 - (2.2314) e^{-2t} \cos(4t - 0.4636)]}_{\text{particular}}$$